

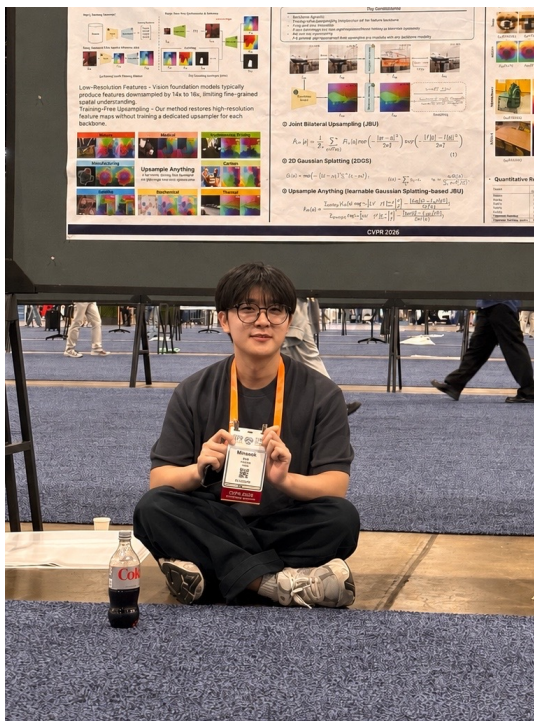
Domain-Adaptive Data Assimilation for Global AI Weather Forecasting

Minseok Seo¹, Noah Brenowitz², Doyi Kim¹, Hyesook Lee¹, Changick Kim¹

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About Me



Minseok Seo (서민석)
Ph.D student at KAIST

Research topic

Test-time Optimization
Domain Adaptation

Research Experiences (Weather Forecasting)

- **NVIDIA (INTERN)** , Research Scientist,, London, UK (July 2026 - Sep 2026)
- **SI-Analytics (military service)** , Research Scientist , Daejeon, Korea (Mar 2022 - Sep 2025)

Publication

Upsample Anything: A Simple and Hard to Beat Baseline for Feature Upsampling

Minseok Seo, Mark Hamilton, Changick Kim (KAIST, Microsoft, MIT)
CVPR 2026 (Compute Gold Star / Transparency Champion)

RainODE: Continuous-Time Precipitation Forecasting with Latent Neural ODEs

Yeeun Seong*, Doyi Kim*, Minseok Seo, and Changick Kim (KAIST)
ECCV 2026 (Project Lead)

Station2Radar: query-conditioned gaussian splatting for precipitation field

Doyi Kim, Minseok Seo, Changick Kim (KAIST)
ICLR 2026 (Project Lead)

Data-driven Precipitation Nowcasting Using Satellite Imagery

Young-Jae Park, Doyi Kim, Minseok Seo, Hae-Gon Jeon, Yeji Choi
AAAI 2025 (ORAL) (Project Lead)

Probabilistic Weather Forecasting with Deterministic Guidance-based Diffusion Model

Donggeun Yoon*, Minseok Seo*, Doyi Kim, Yeji Choi, and Donghyeon Cho
ECCV 2024 (Project Lead)

Long-Term Typhoon Trajectory Prediction: A Physics-Conditioned Approach Without Reanalysis Data

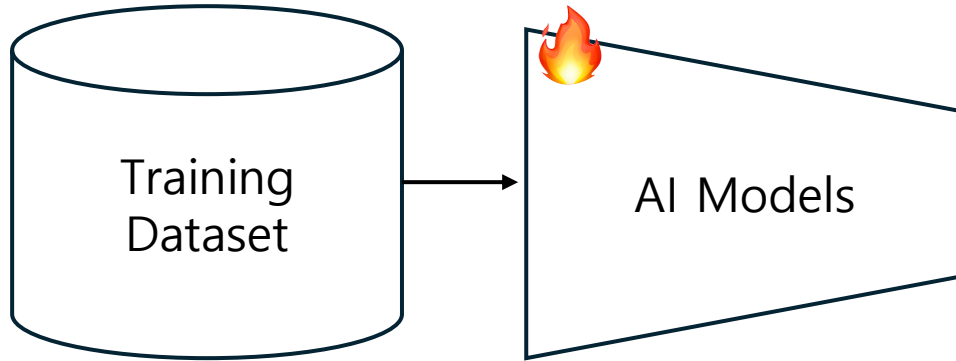
Young-Jae Park*, Minseok Seo*, Doyi Kim, Hyeri Kim, Sanghoon Choi, Beomkyu Choi, Jeongwon Ryu, Sohee Son, Hae-Gon Jeon, Yeji Choi
ICLR 2024 (Spotlight)

Weather4cast at neurips 2022: Super-resolution rain movie prediction under spatio-temporal shifts

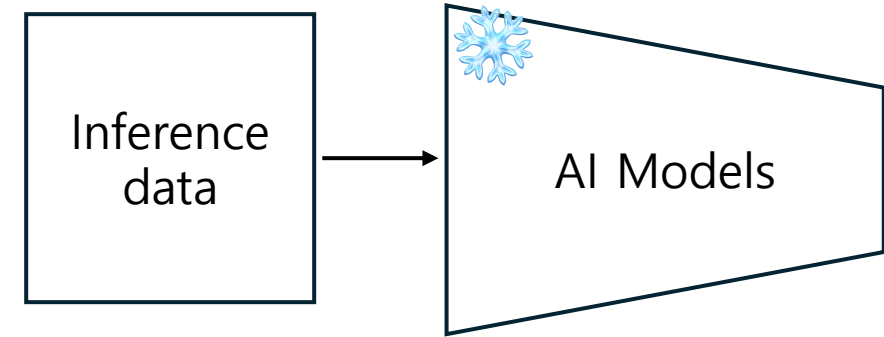
Weather4Forecast (Winner) (Project Lead)
NeurIPS 2022 competition track

What Is Test-Time Optimization?

Standard AI Model Workflow

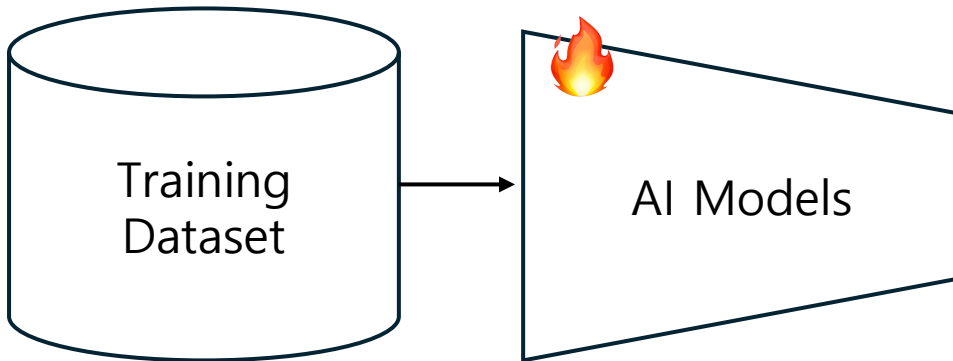


Phase 1. Training

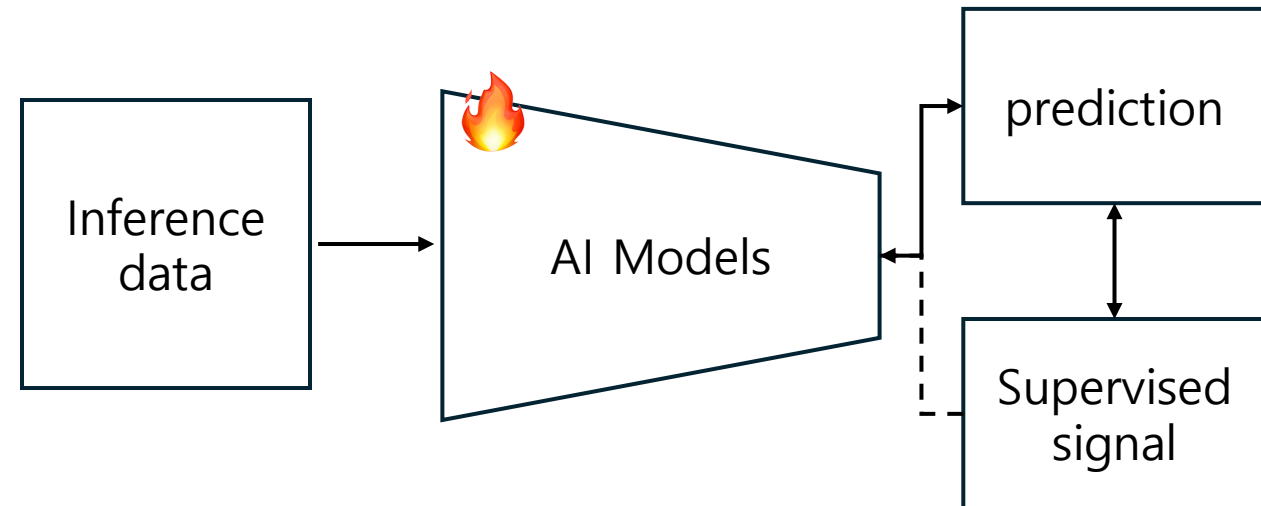


Phase 2. Inference

Test-time optimization Workflow

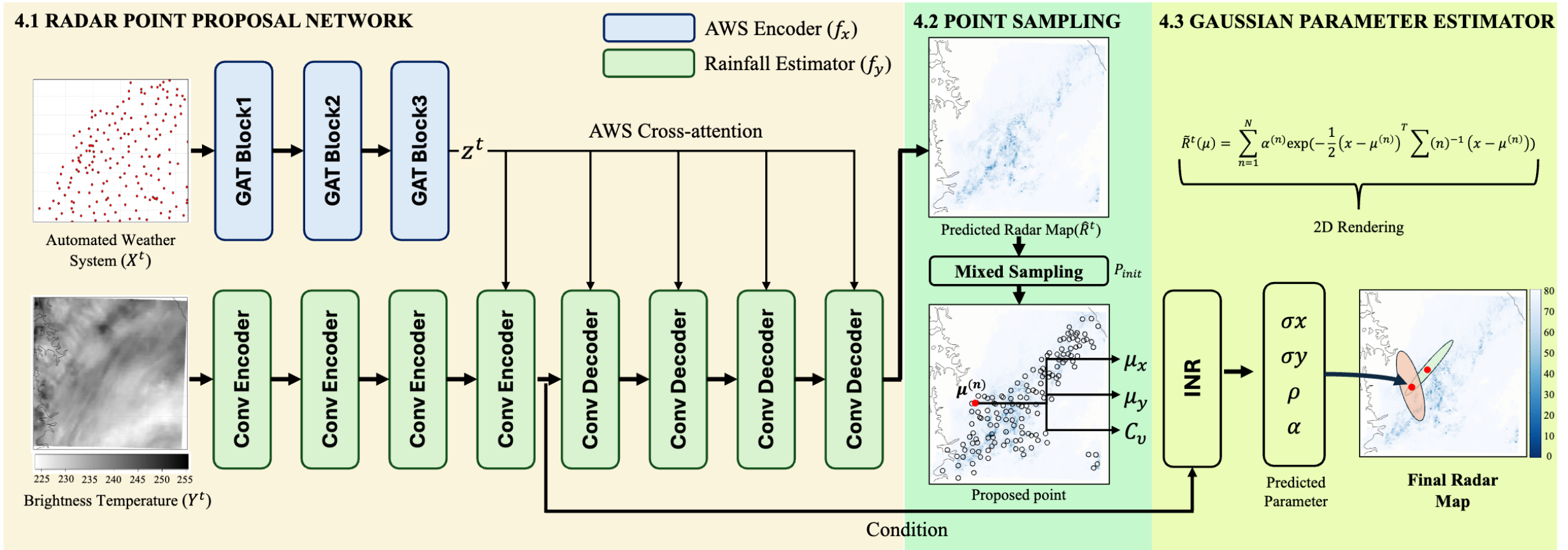


Phase 1. Training



Phase 2. Inference

Observation-Guided Test-Time Optimization: Station2Radar (1)



Observation-Guided Test-Time Optimization: Station2Radar (2)

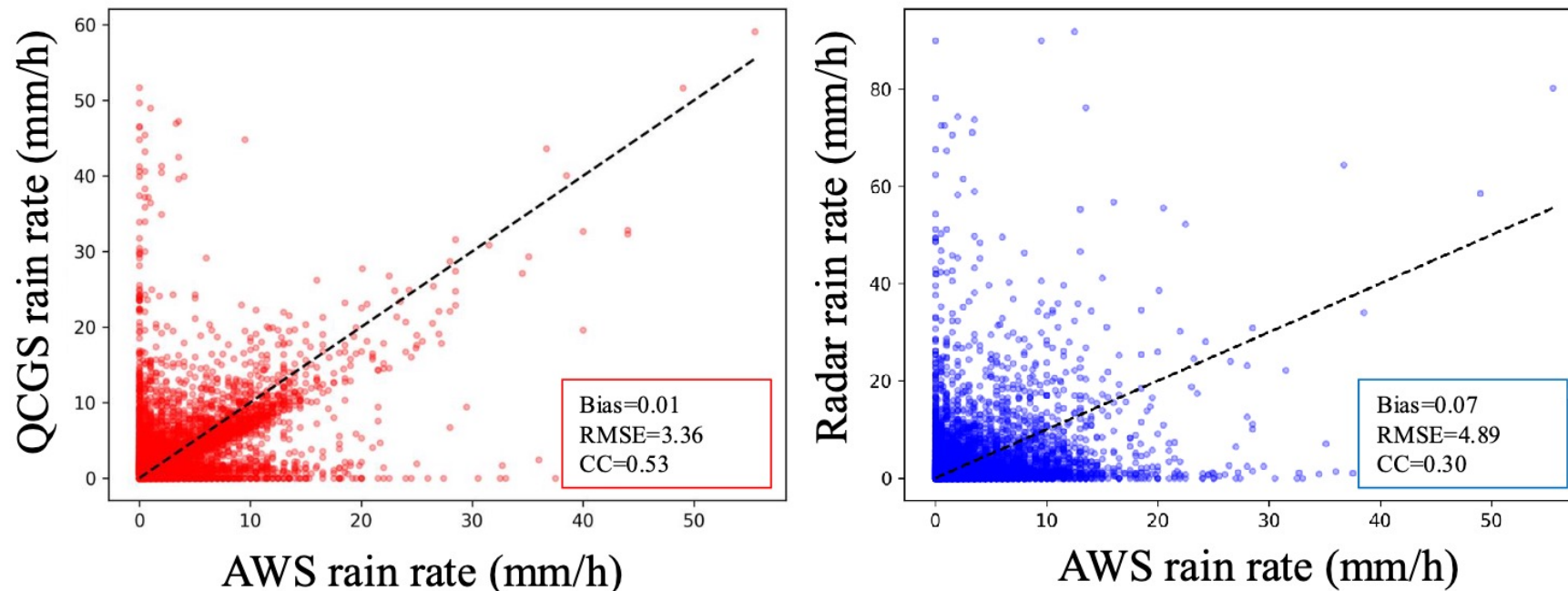
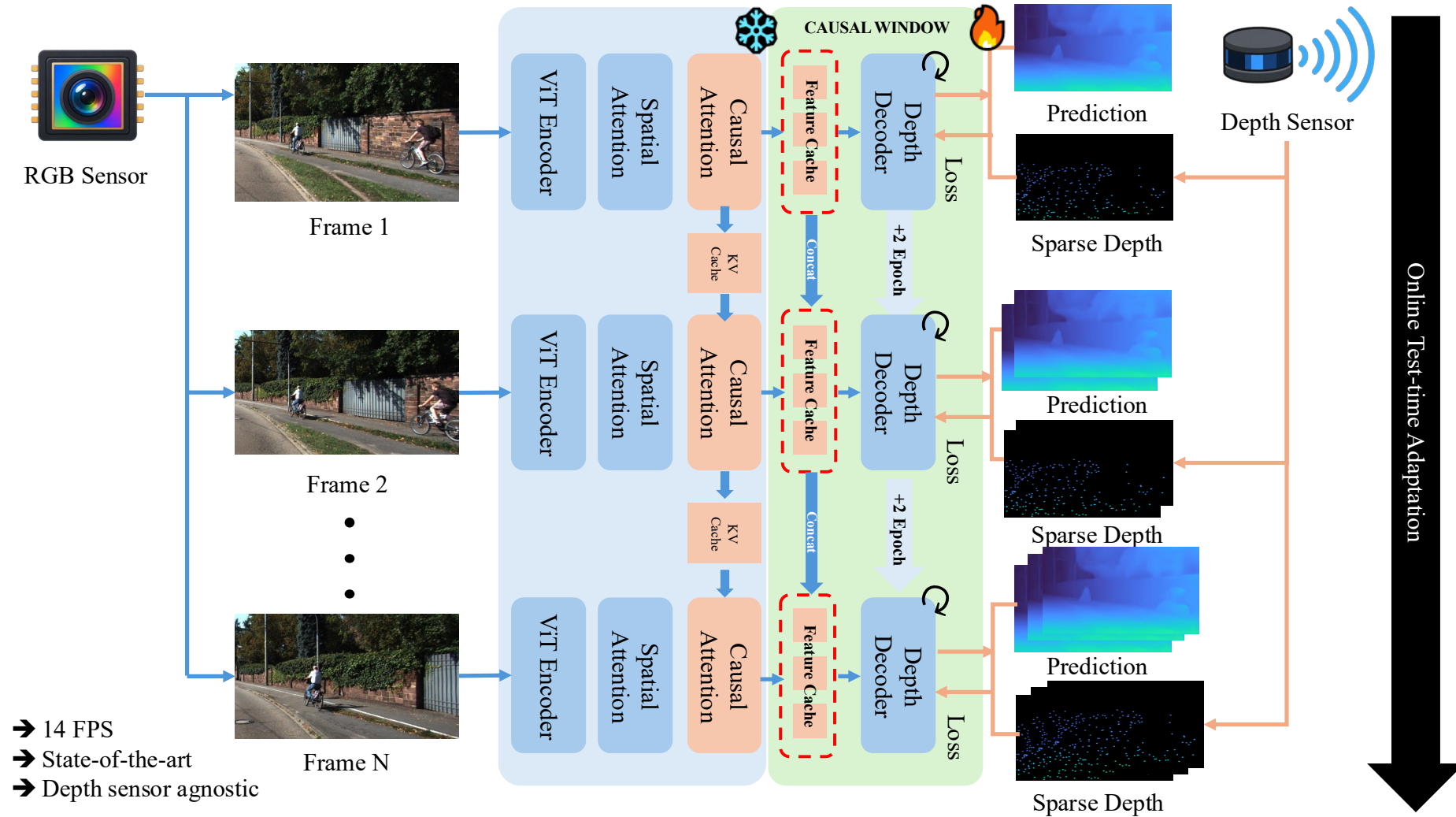
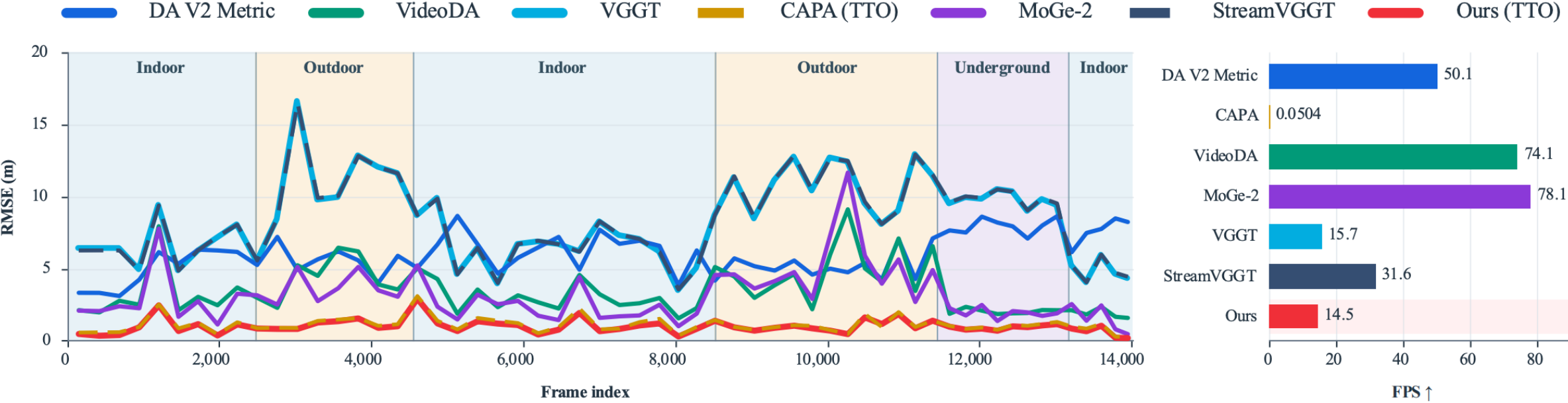


Figure 6: Bias, RMSE, and correlation coefficient (CC) of AWS rain rate compared with QCGS and radar. QCGS consistently achieves lower bias and RMSE and higher CC relative to radar, demonstrating closer agreement with gauge observations.

Observation-Guided Test-Time Optimization: StreamTTO (1)



Observation-Guided Test-Time Optimization : StreamTTO (2)



Why Does TTO Work? Sensitivity to Distribution Shift (1)



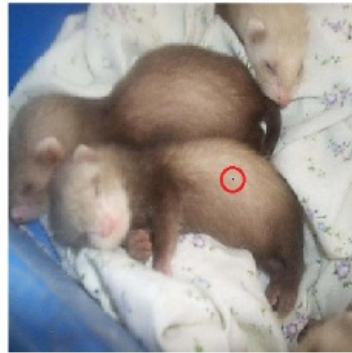
Cup(16.48%)
Soup Bowl(16.74%)



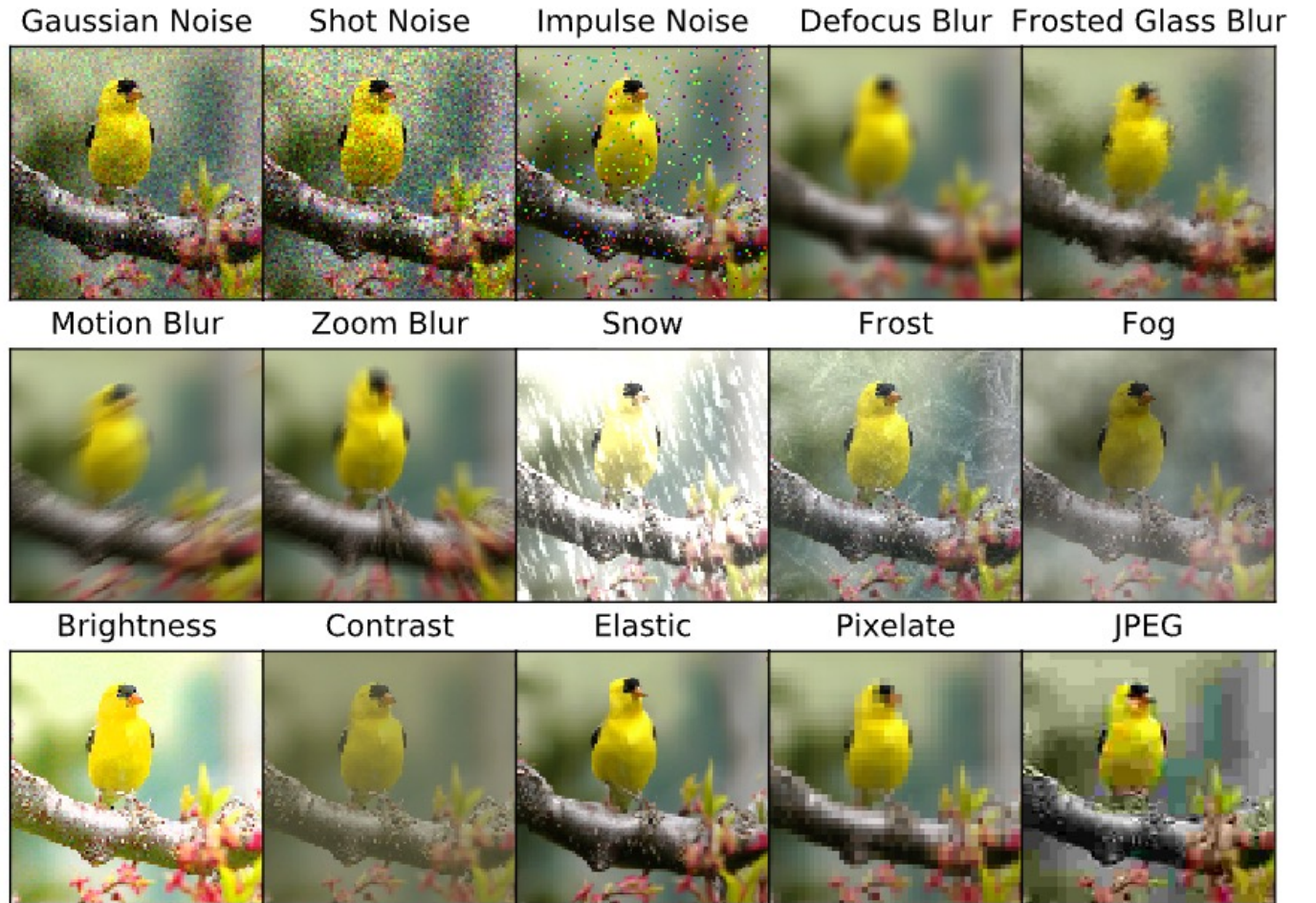
Bassinet(16.59%)
Paper Towel(16.21%)



Teapot(24.99%)
Joystick(37.39%)



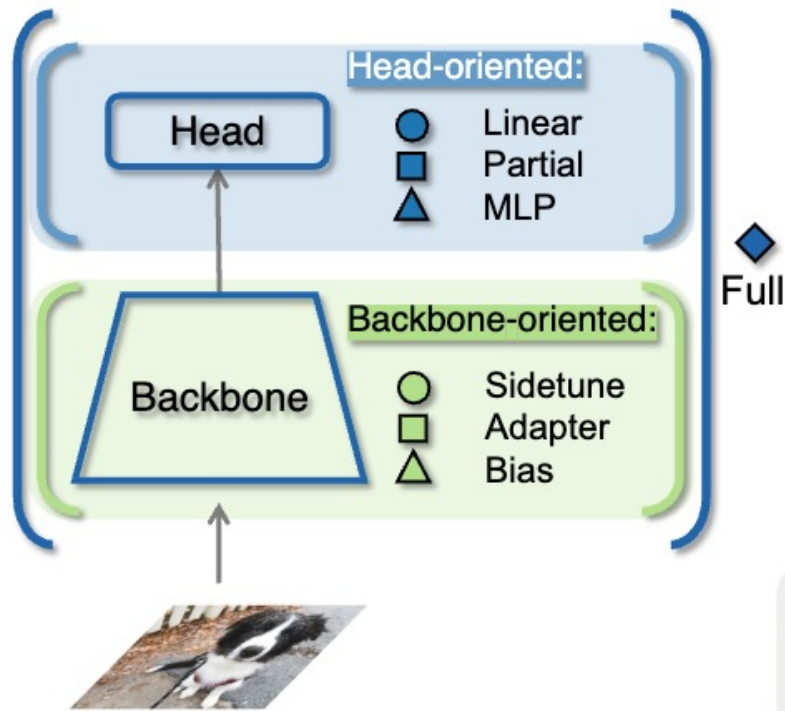
Hamster(35.79%)
Nipple(42.36%)



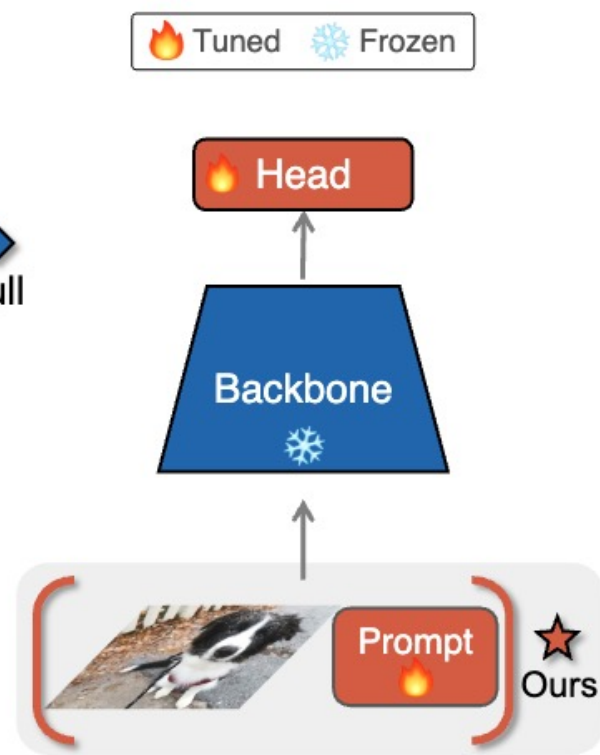
[3] Su, Jiawei, Danilo Vasconcellos Vargas, and Kouichi Sakurai. "One pixel attack for fooling deep neural networks." *IEEE Transactions on Evolutionary Computation* 23.5 (2019): 828-841.

[4] Hendrycks, Dan, and Thomas Dietterich. "Benchmarking neural network robustness to common corruptions and perturbations." *arXiv preprint arXiv:1903.12261* (2019).

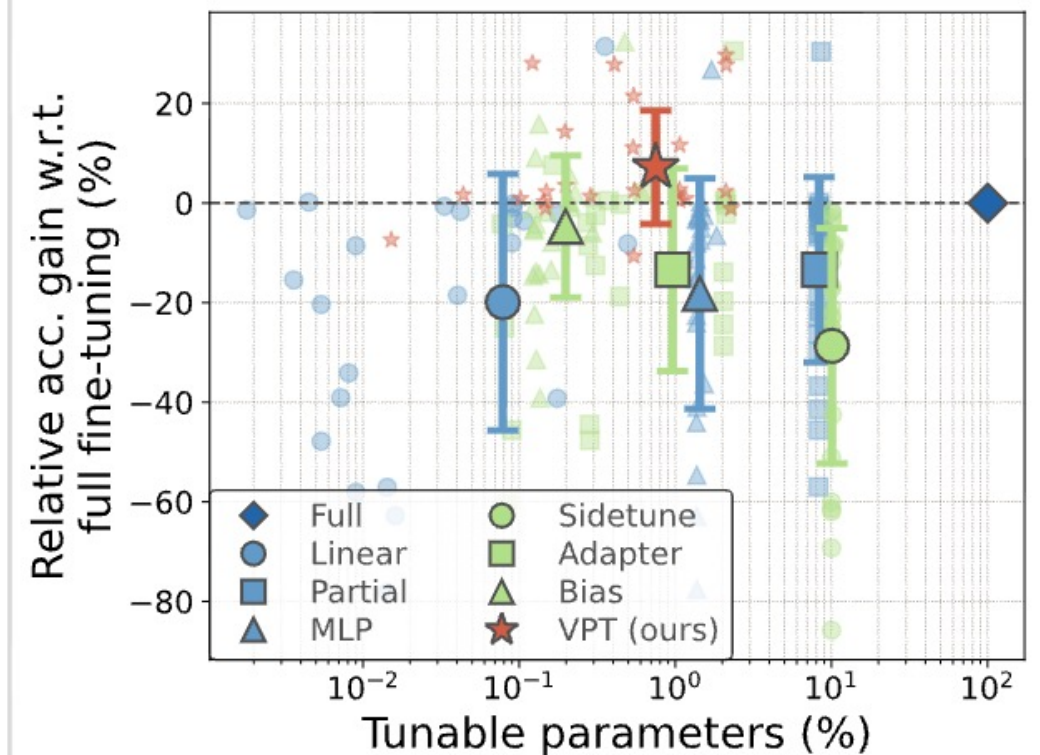
Why Does TTO Work? Sensitivity to Distribution Shift (2)



(a) Existing tuning protocols

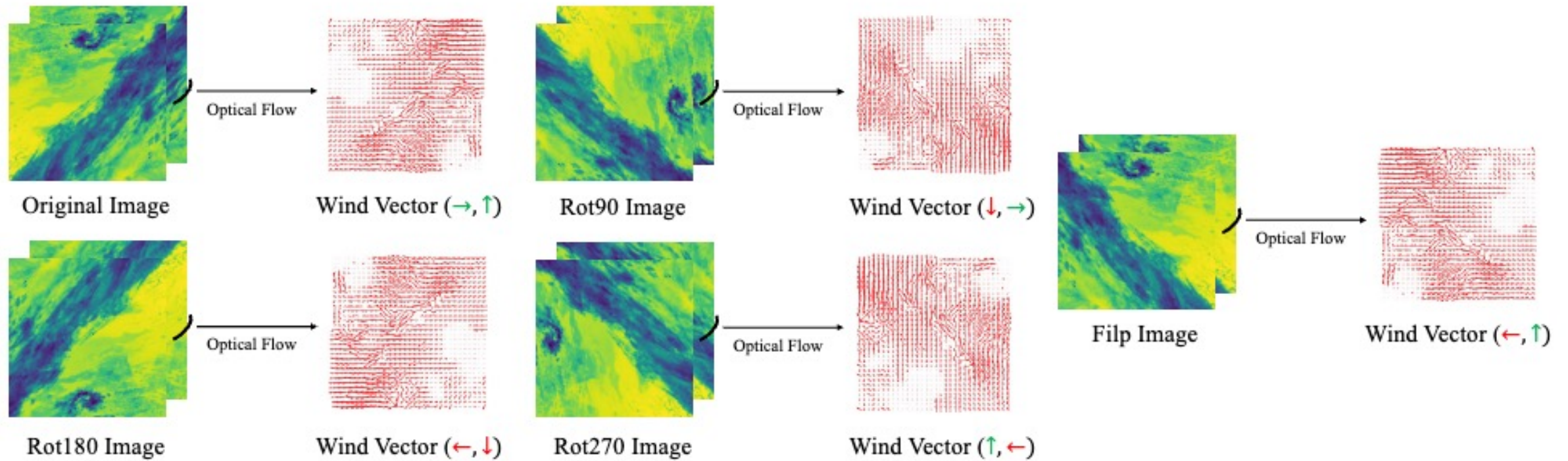


(b) Visual-Prompt Tuning (VPT)

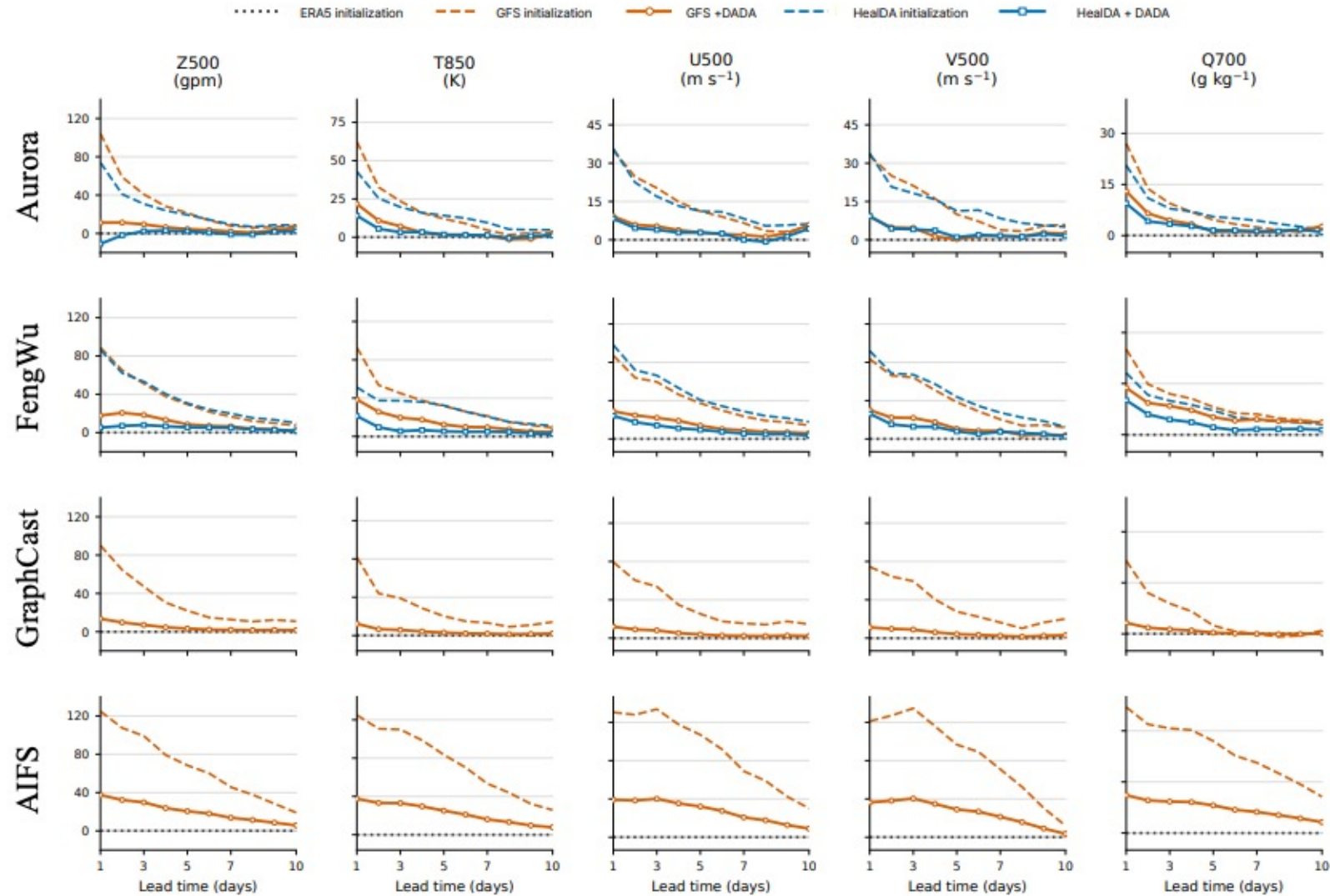


(c) Results on visual classification tasks

Why Does TTO Work? Sensitivity to Distribution Shift (3)

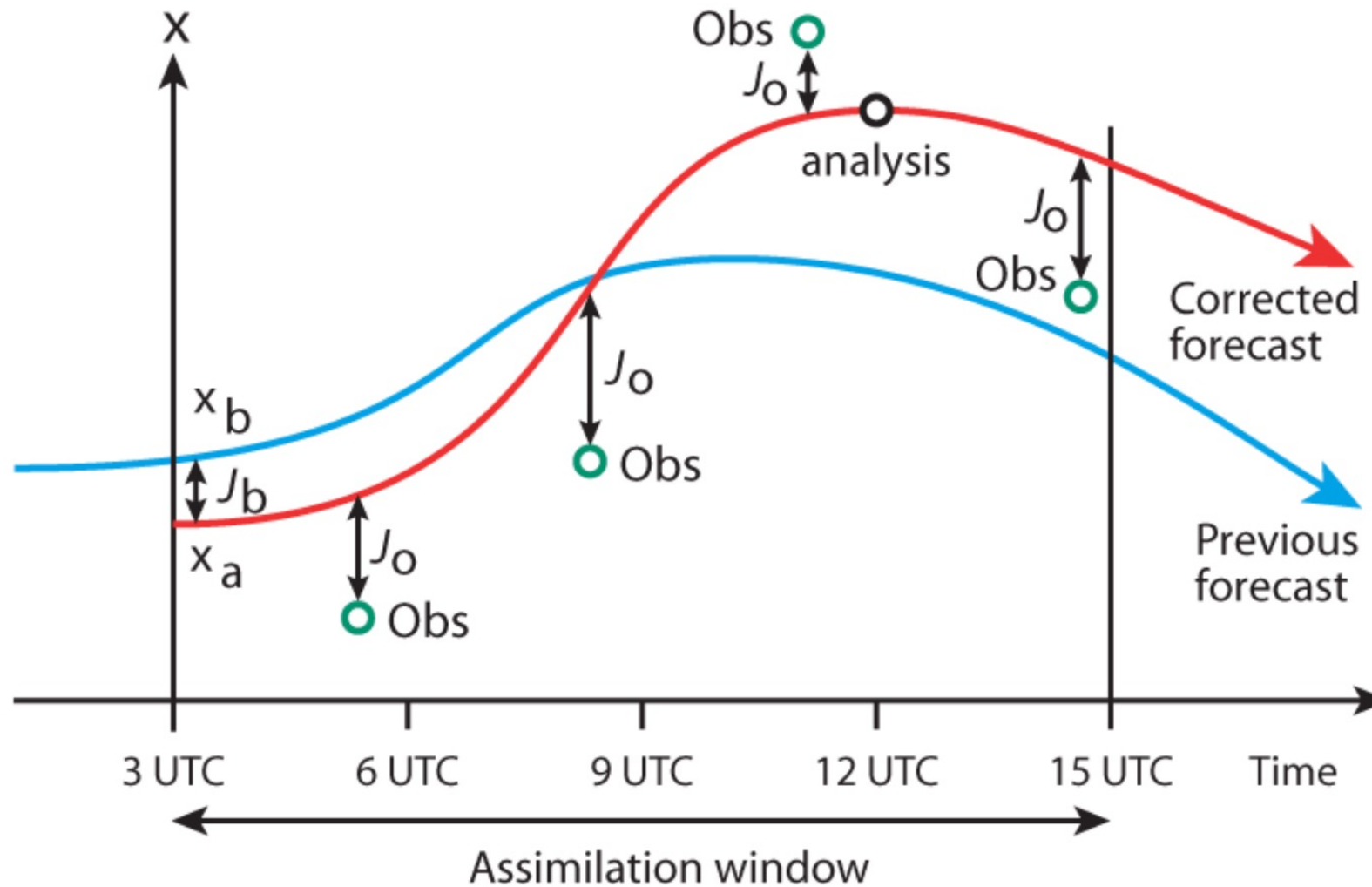


Distribution Shift in Weather Forecasting



Latitude-weighted RMSE difference from ERA5 initialization (%)

Data Assimilation Naturally Addresses Distribution Shift



4D-Var: Optimizing the Initial State over Time

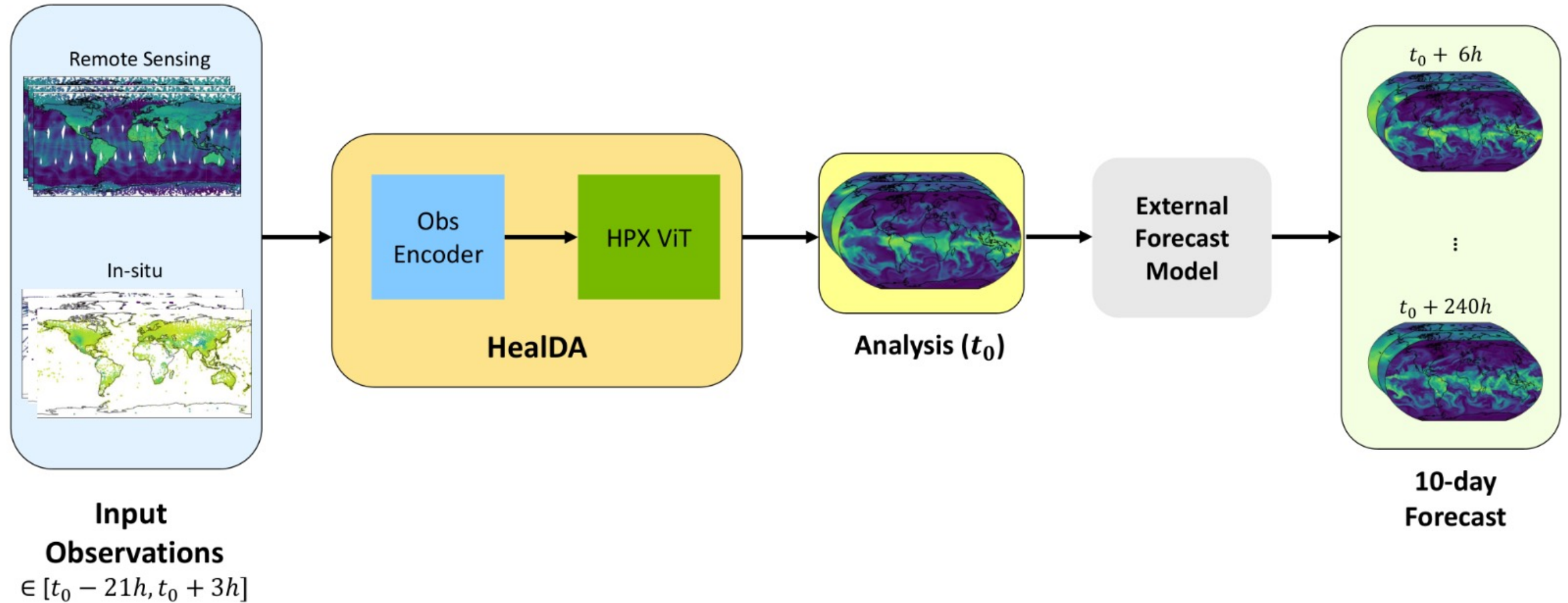
The diagram illustrates the 4D-Var cost function, which is minimized to find the optimal initial state $\mathbf{x}_0^*$. The function is composed of two main terms: a background term and an observation term. The background term, $\|\mathbf{x}_0 - \mathbf{x}_b\|_{\mathbf{B}^{-1}}^2$, represents the difference between the analysis field $\mathbf{x}_0$ and the background field $\mathbf{x}_b$, weighted by the background error covariance $\mathbf{B}^{-1}$. The observation term, $\sum_k \|\mathcal{H}_k(\mathcal{M}_{0 \rightarrow k}(\mathbf{x}_0)) - \mathbf{y}_k\|_{\mathbf{R}_k^{-1}}^2$, represents the difference between the observation operator $\mathcal{H}_k$ applied to the model $\mathcal{M}_{0 \rightarrow k}(\mathbf{x}_0)$ and the observations $\mathbf{y}_k$, weighted by the observation error covariance $\mathbf{R}_k^{-1}$. The entire cost function is enclosed in large square brackets.

$$\mathbf{x}_0^* = \arg \min_{\mathbf{x}_0} \left[\underbrace{\|\mathbf{x}_0 - \mathbf{x}_b\|_{\mathbf{B}^{-1}}^2}_{\text{Background}} + \sum_k \underbrace{\|\mathcal{H}_k(\mathcal{M}_{0 \rightarrow k}(\mathbf{x}_0)) - \mathbf{y}_k\|_{\mathbf{R}_k^{-1}}^2}_{\text{Observation}} \right]$$

Annotations in the diagram include:

- Analysis field**: Points to $\mathbf{x}_0$.
- Background field**: Points to $\mathbf{x}_b$.
- Observation operator**: Points to $\mathcal{H}_k$.
- Background**: Points to the background term.
- Observation**: Points to the observation term.
- background error covariance**: Points to $\mathbf{B}^{-1}$.
- observation error covariance**: Points to $\mathbf{R}_k^{-1}$.

HealDA: Highlighting the importance of initial errors in end-to-end AI weather forecasts



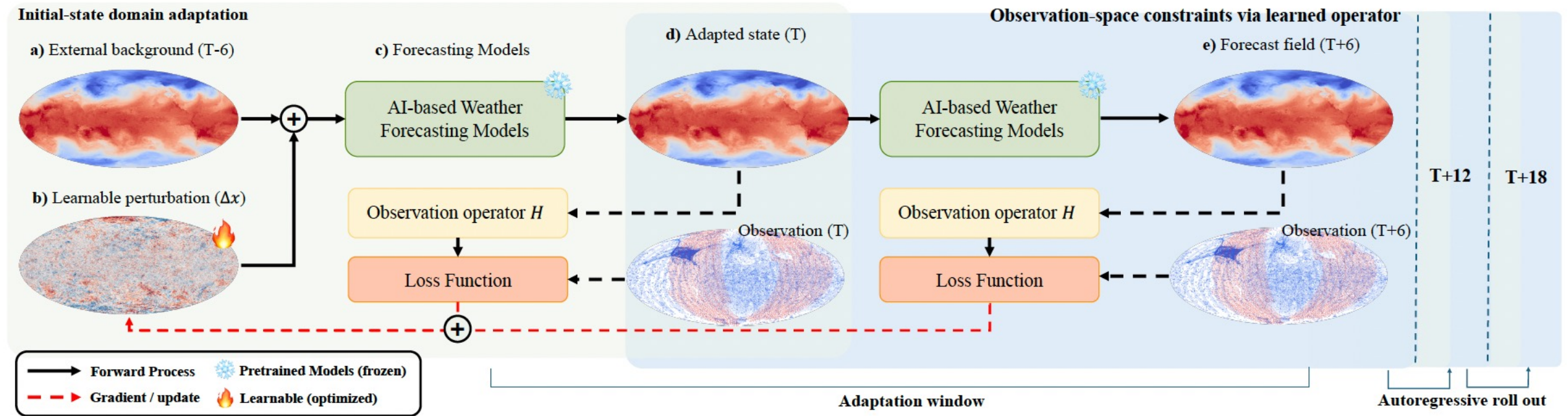
HealDA: Highlighting the importance of initial errors in end-to-end AI weather forecasts

(a) RMSE Scores (vs ERA5 unless otherwise indicated)

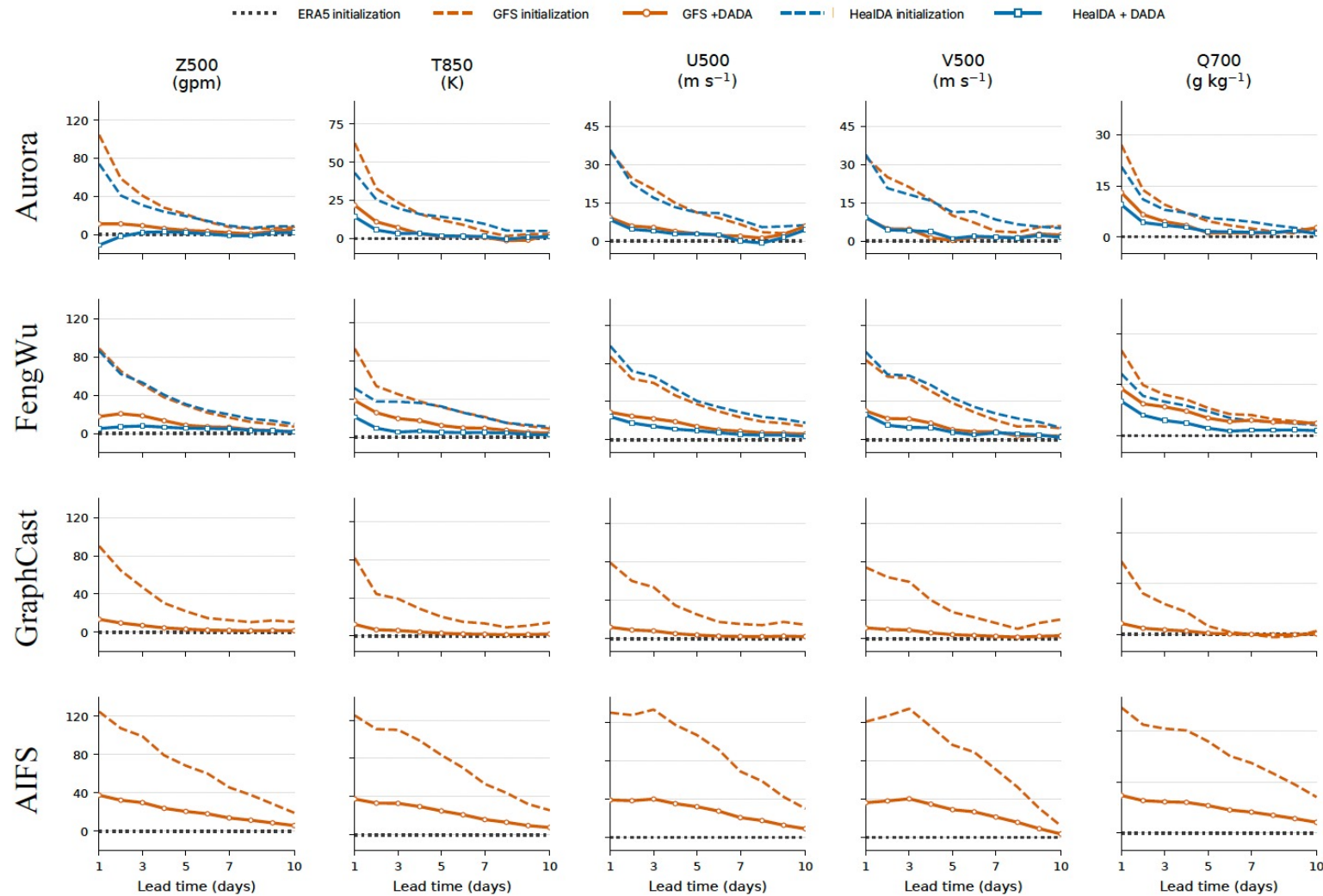
Method	Validation Protocol	IC RMSE			RMSE at 1 day			RMSE at 5 days		
		Z500	T850	U500	Z500	T850	U500	Z500	T850	U500
ERA5 [32, Fig. 12] [‡]	~ 2018	–	0.34	0.74	–	–	–	–	–	–
Aardvark [15] [*]	1°, 2018	62	0.94	2.3	93	1.0	2.8	450	2.2	5.9
FuXi Weather [18] [*]	0.25°, 2023–2024	80	1.0	2.2	100	1.1	2.5	390	2.1	5.3
XiChen [17] [*]	1.40625°, 2023	100	1.1	–	150	1.2	–	490	2.3	–
IFS ENS [†]	1°, 2022	26	0.71	1.11	47	0.77	1.46	280	1.62	4.22
HealDA-initialized FCN3 [†]	HPX64, 2022	47	0.70	1.68	67	0.78	1.98	325	1.76	4.71
HealDA-initialized Atlas ^{†1}					66	0.81	1.94	308	1.73	4.55

[‡] Spread of DA ensemble reported. ^{*} Single-member forecast. Trained with multi-step loss functions. [†] Ensemble mean scores reported.

Domain-Adaptive Data Assimilation for Global AI Weather Forecasting

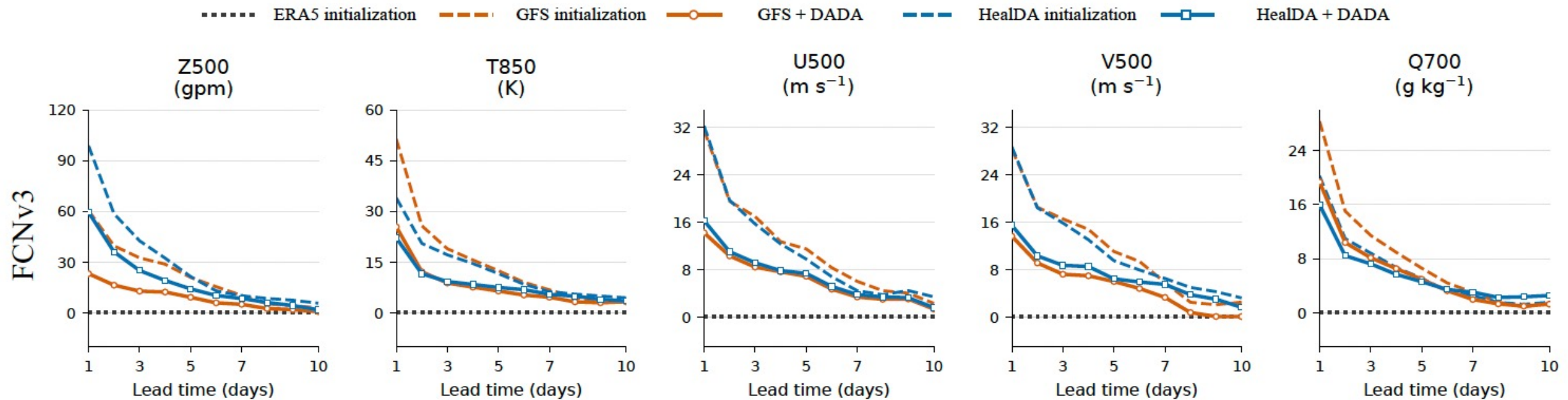


Adaptation across forecasting models and initial conditions



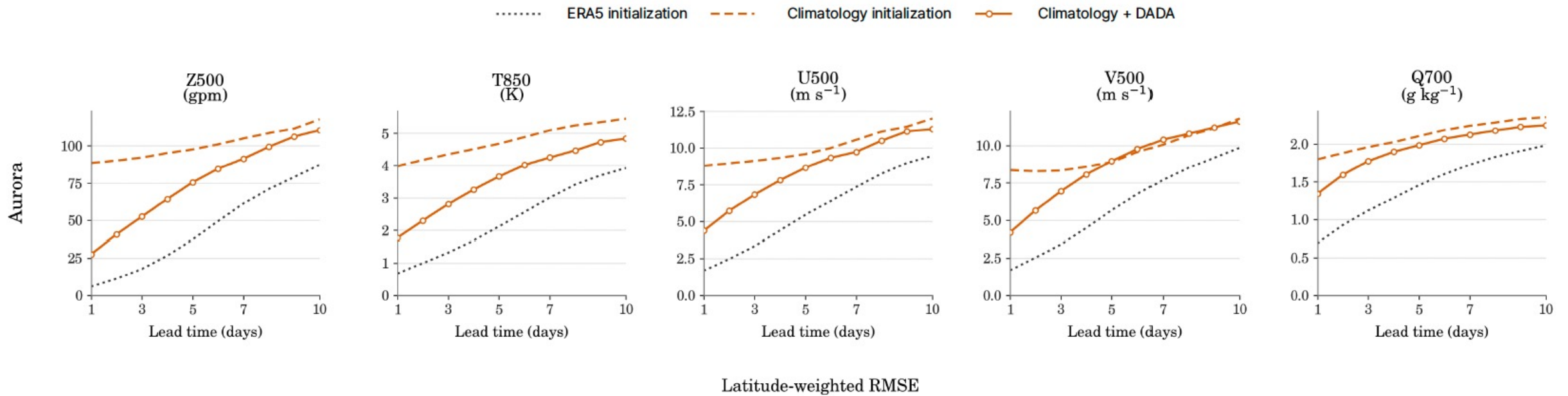
Latitude-weighted RMSE difference from ERA5 initialization (%)

Probabilistic forecast skill with FCNv3

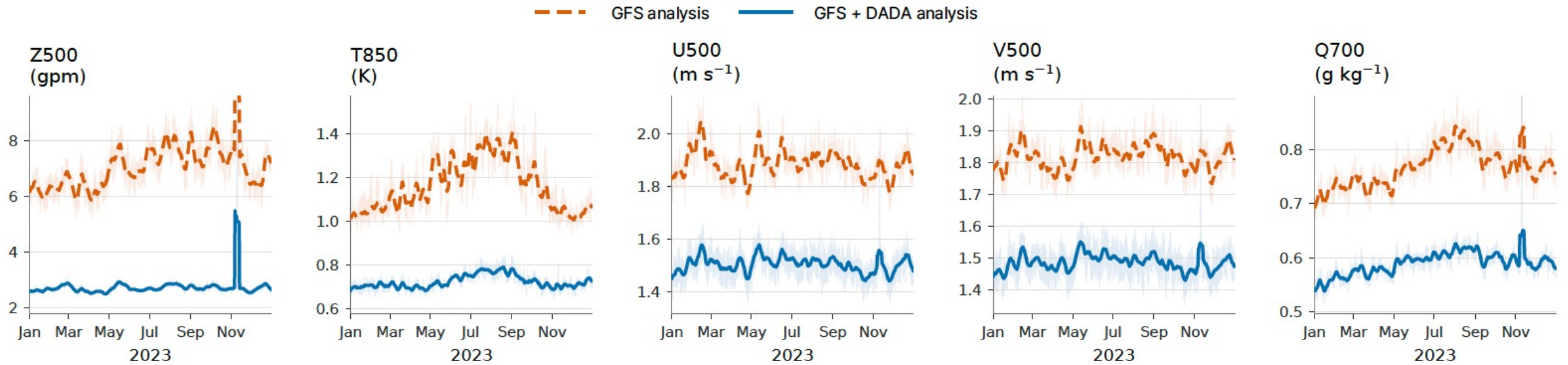


CRPS difference from ERA5 initialization (%)

Assimilation from a climatological background



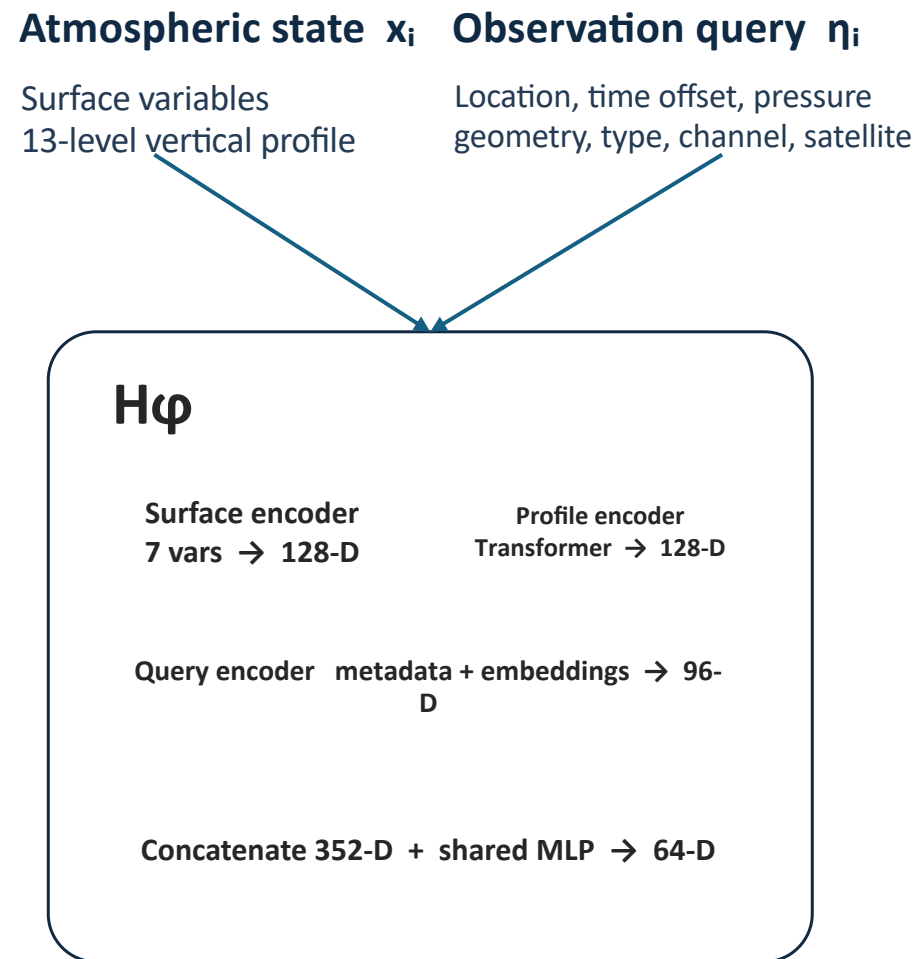
Adaptation of GFS analysis fields throughout 2023



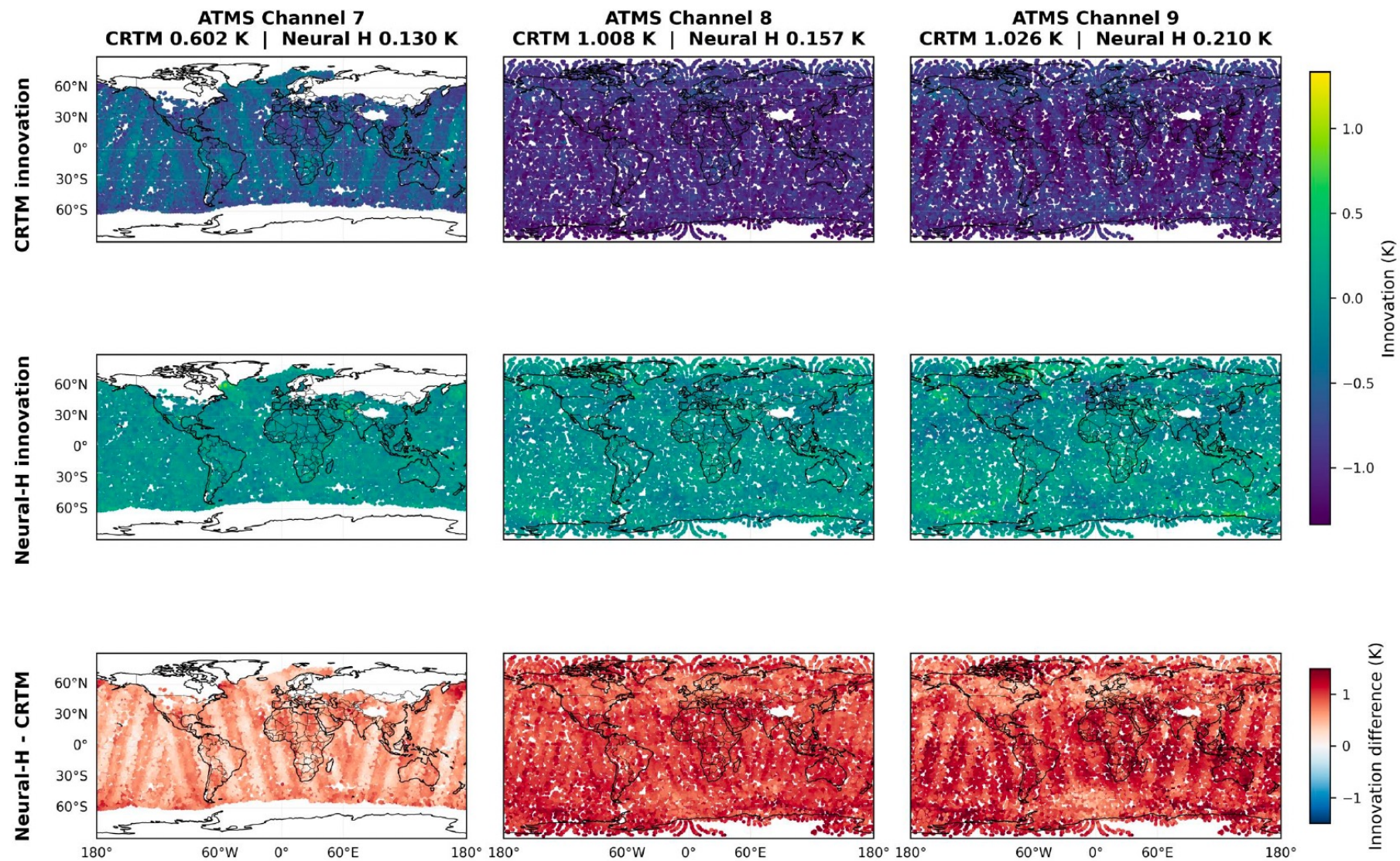
Learned observation operator H

Supplementary Table 1 Observation-space errors (K) for ATMS brightness temperatures. Centered SD is calculated after removing the channel-wise mean GSI/CRTM error.

Channel	H_ϕ RMSE	GSI/CRTM	
		Raw RMSE	Centered SD
ATMS 2	2.476954	3.155379	3.152329
ATMS 3	1.958710	2.625560	2.624673
ATMS 4	1.164067	1.959157	1.707803
ATMS 5	0.460943	1.074024	0.595001
ATMS 6	0.192121	0.408941	0.193317
ATMS 7	0.137100	0.607351	0.212642
ATMS 8	0.173212	0.992811	0.140191
ATMS 9	0.237705	1.009791	0.202866
ATMS 10	0.577272	0.716508	0.210620
ATMS 11	1.347094	0.692231	0.220185
ATMS 12	2.739497	0.793479	0.220285
ATMS 13	4.331110	1.065720	0.311399
ATMS 14	5.365727	1.181464	0.450714
ATMS 15	5.810463	1.011856	0.699220
ATMS 16	3.129026	3.432366	3.428995
ATMS 17	1.964668	2.423137	2.339071
ATMS 18	1.276355	1.653800	1.229600
ATMS 19	1.383326	1.398924	1.170310
ATMS 20	1.522965	1.392776	1.199080
ATMS 21	1.686363	1.348542	1.252914
ATMS 22	1.782852	1.314962	1.314958

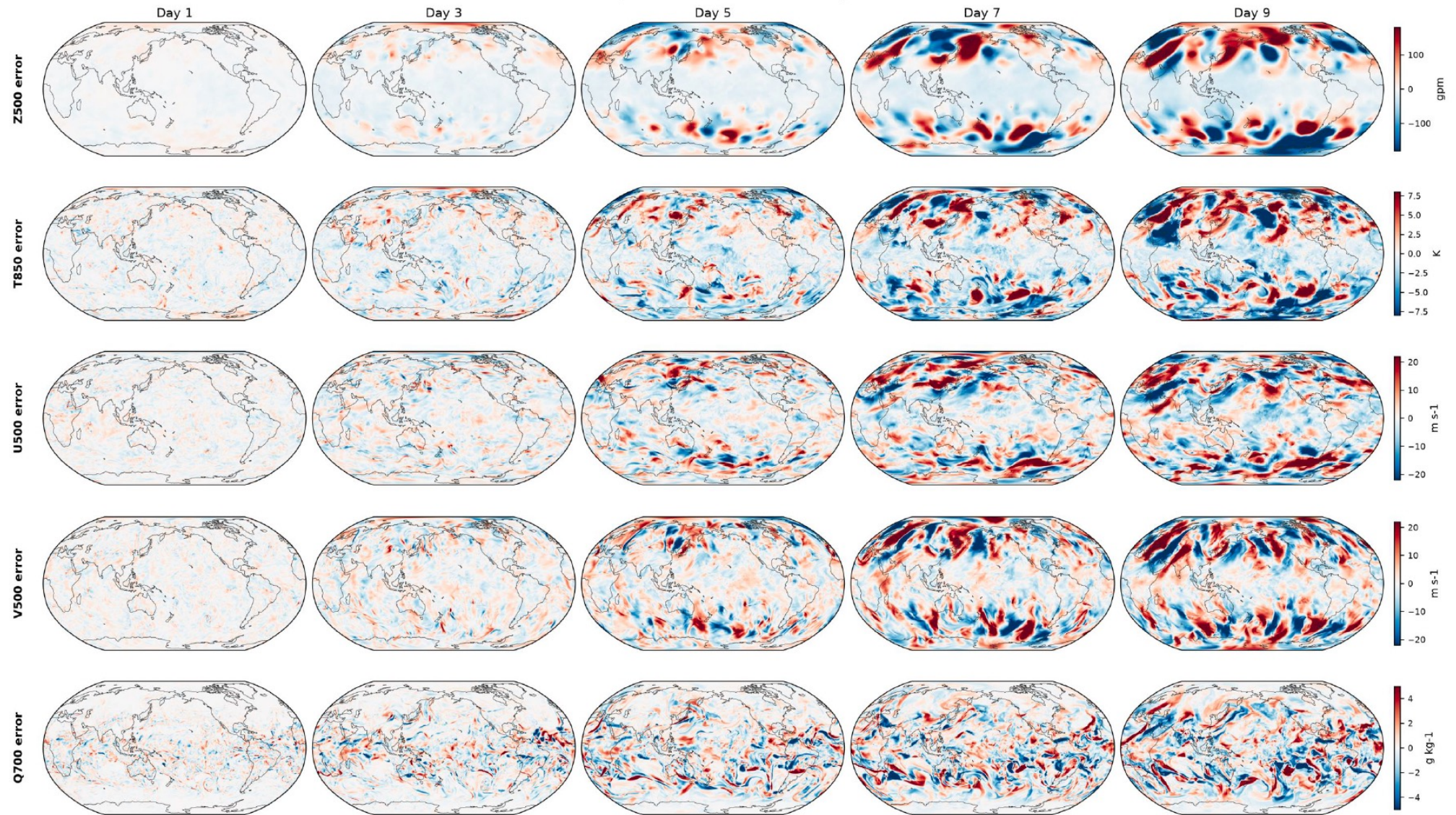


Learned observation operator H



16,384 matched FOVs per channel; no spatial interpolation

Visualization of Spatial Forecast Errors



Conclusion and Discussion

What We show

- DADA is the first framework to explicitly address the domain gap caused by changes in background states.
- DADA improves forecast performance with both AI-based and NWP-based backgrounds.
- DADA complements existing data assimilation systems because it still requires an informative background state.

Where the Field May Go

- Observation-to-prediction models such as AI-DOP avoid this particular background-state domain gap by design.
- If fully end-to-end observation-to-forecast learning becomes practical, DADA may no longer be necessary.
- However, the vast amount of accumulated gridded training data makes a complete transition difficult in the near term.

Practical Pathway

Observations → Data Assimilation → Background State → DADA → AI Forecast

Open to Collaboration

AI for weather and climate, and observation-driven research across domains